

TAL 044

Low Voltage Alternator - 4 pole

Three-phase 70 to 200 kVA - 50 Hz / 88 to 250 kVA - 60 Hz
Dedicated single-phase 57 to 82 kVA - 50 Hz / 80 to 125 kVA - 60 Hz
Electrical and mechanical data

LEROY-SOMER[™]

Nidec
All for dreams

TAL 044 - Three-phase & Single-phase

Adapted to needs

The TAL alternator range is designed to meet the needs of general applications such as prime power and stand-by.

Compliant with international standards

The TAL range complies with international standards and regulations: IEC 60034 and derivative.

The range is designed, manufactured and marketed in an ISO 9001 and 14001 environment.

Electrical design

- Class H insulation
- Shunt excitation
- Low voltage winding:
 - Three-phase 50 Hz: 380V - 400V - 415V - 440V / 220V - 230V - 240V
 - 60 Hz: 380V - 416V - 440V - 480V / 220V - 208V - 240V
 - Single-phase 50 Hz: 230V
 - 60 Hz: 240V
- 4-terminal plates in 6-wire version
- Optimized performance

Robust design

- Compact and rugged assembly to withstand engine vibrations
- Steel frame
- Aluminum flanges and shields
- Single bearing design compatible with most diesel engines
- Sealed for life single bearing
- Direction of rotation: clockwise and counterclockwise without derating



Excitation and regulation system suited to the application

	Excitation system				Regulation options		
	AVR	SHUNT	AREP (option)	PMG (option)	ULC/US	Remote voltage potentiometer	C.T. for paralleling
Three-phase 6-wire	R120	Standard					
	R150	Option				√	
	R180		Standard	Standard		√	√
	D350	Option	Option	Option	√	√	√
Three-phase 12-wire	R120	Standard					
	R250	Option			√	√	
	R180		Standard	Standard		√	√
	D350		Option	Option	√	√	√
Single-phase	R121	Standard				√	
	R250	Option			√	√	

√: Possible option

Compact terminal box

- Easy access to AVR and terminals
- Possibility of current transformer for parallel operation

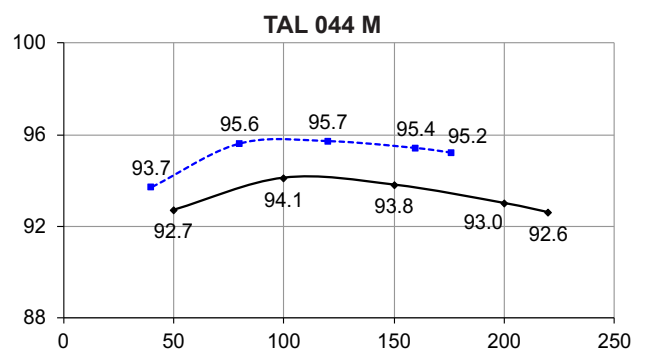
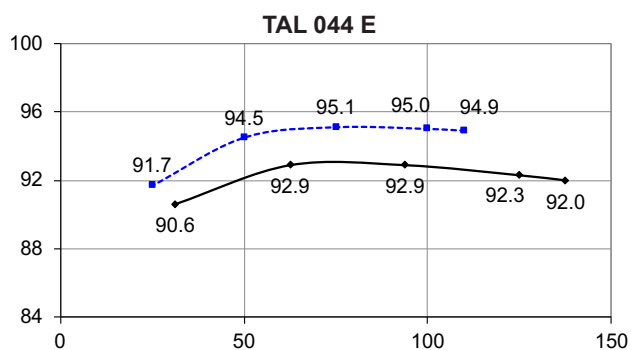
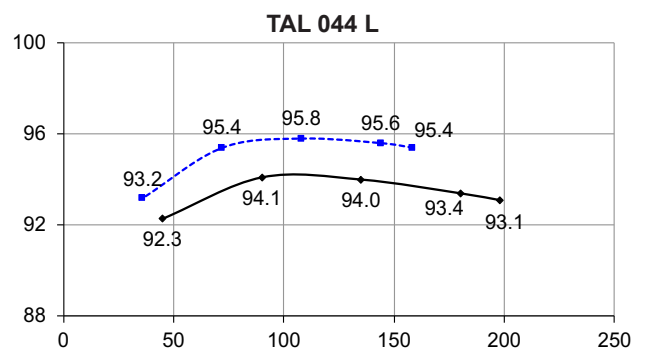
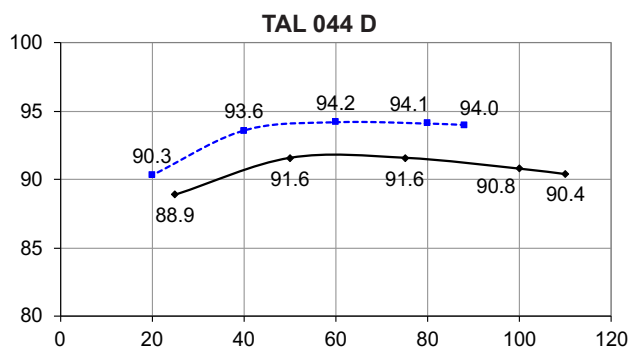
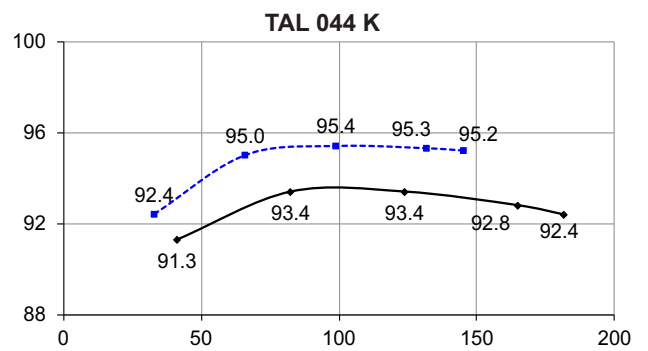
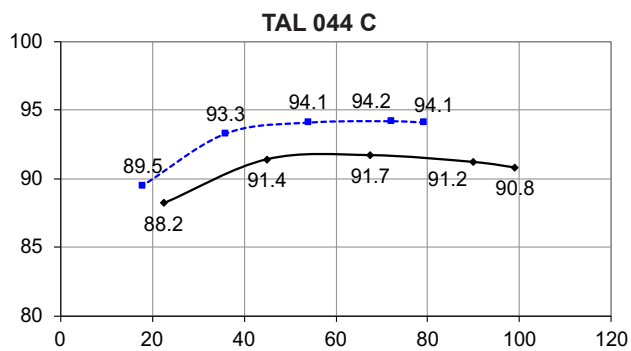
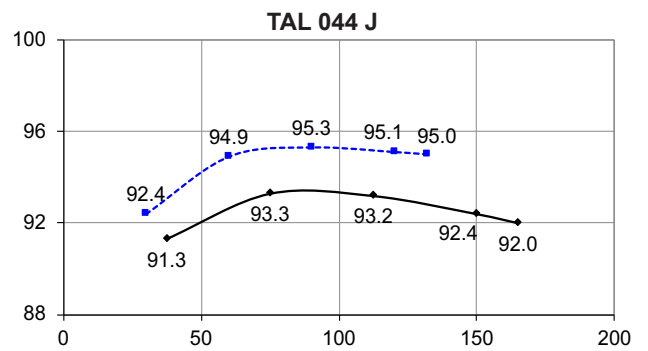
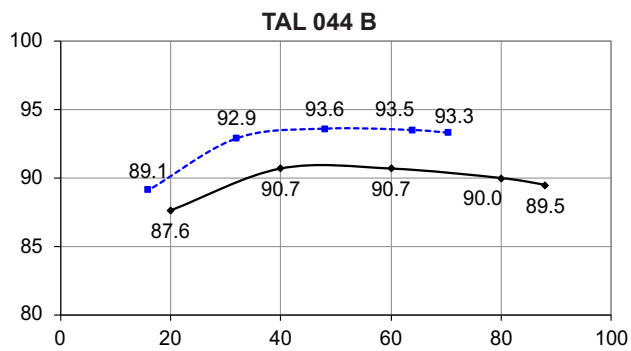
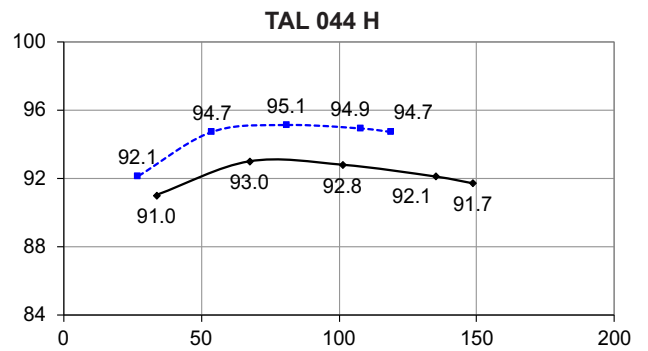
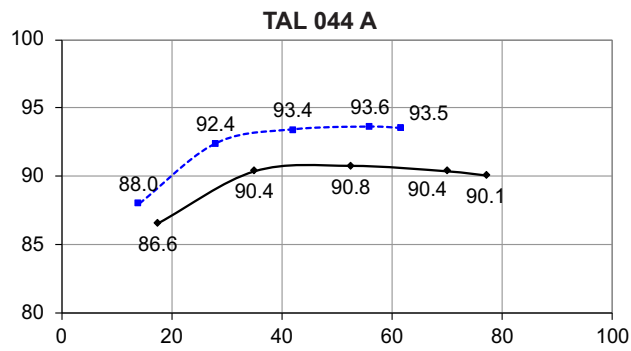
Environment and protection

- IP Code IP 23
- Standard winding protection for non-harsh environment with relative humidity $\leq 95\%$

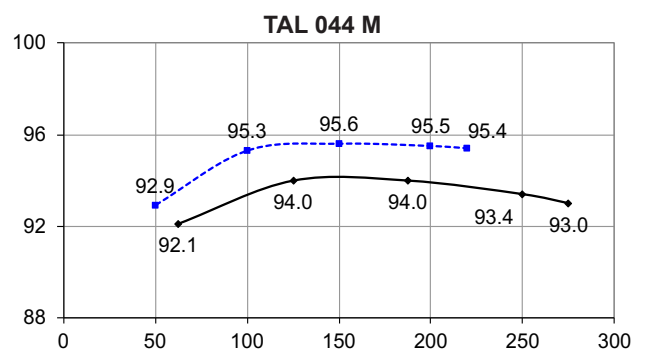
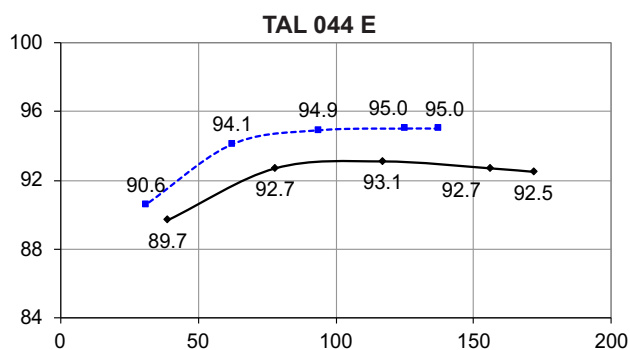
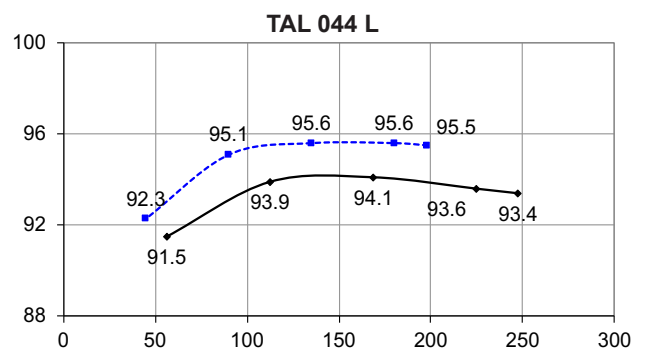
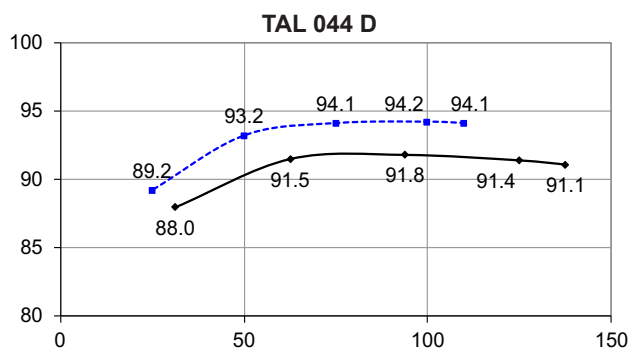
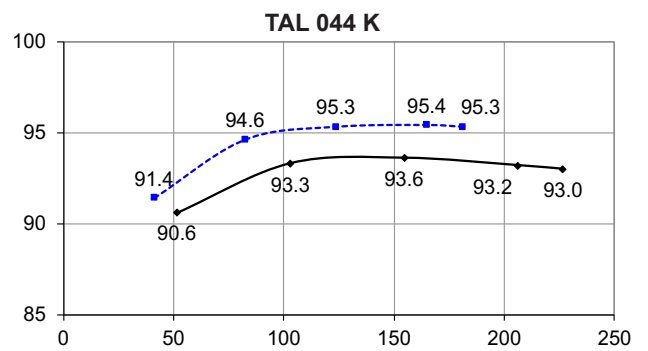
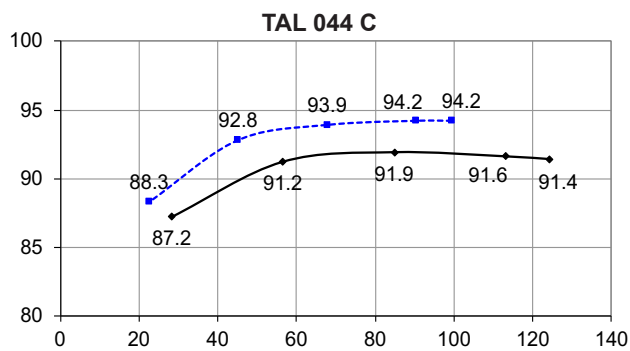
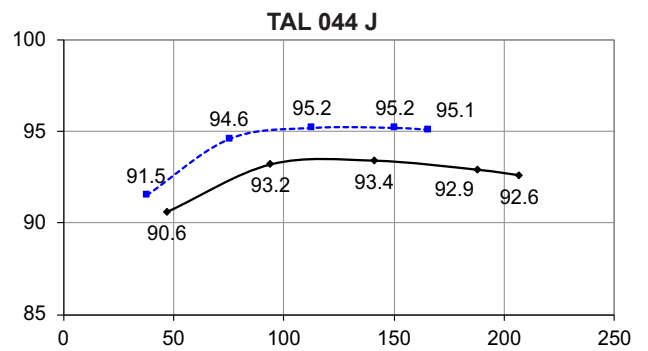
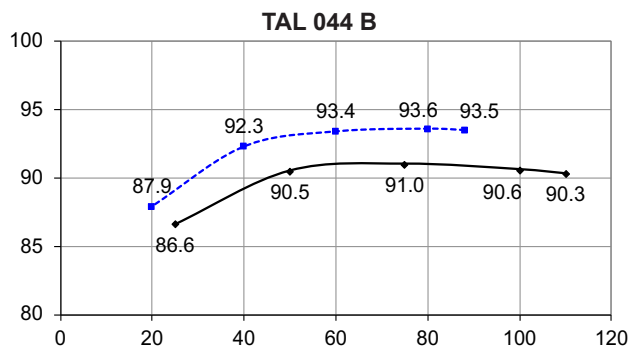
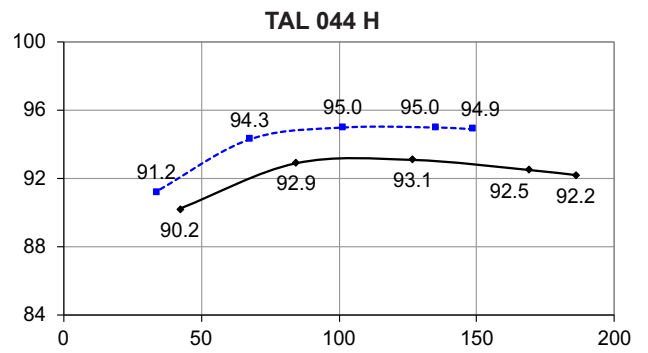
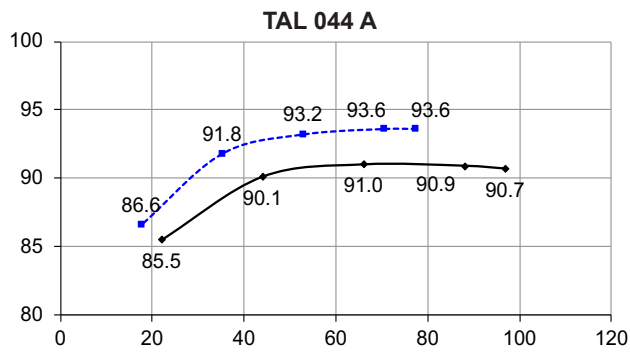
Available options

- Three-phase 12-wire with 8-terminal plates
- AREP or PMG excitation
- ULC/us
- Customized painting (machine not painted as standard)
- Space heaters
- Flying leads
- Droop kit for alternator paralleling
- Dedicated single-phase
- Stator sensors
- Winding 8 optimized for three-phase 380V / 416V - 60Hz
- Winding protection for harsh environments and relative humidity greater than 95% (system 2 - 4 without derating): for TAL 044 K apply a derating coefficient of 0.97

Efficiencies 400 V - 50 Hz (— P.F.: 0.8) (----- P.F.: 1)



Efficiencies 480 V - 60 Hz (— P.F.: 0.8) (----- P.F.: 1)



Reactances (%). Time constants (ms) - Class H / 400 V

	A	B	C	D	E	H	J	K	L	M
Kcc Short-circuit ratio	0.57	0.5	0.53	0.48	0.43	0.4	0.4	0.42	0.37	0.33
Xd Direct-axis synchro. reactance unsaturated	294	336	307	341	334	361	359	343	343	381
Xq Quadrature-axis synchro. reactance unsaturated	150	171	156	174	170	184	183	175	175	194
T'do No-load transient time constant	2475	2475	2308	2308	2154	2154	2112	2077	2025	2025
X'd Direct-axis transient reactance saturated	11.9	13.6	13.3	14.7	15.5	16.7	17	16.5	16.9	18.8
T'd Short-circuit transient time constant	100	100	100	100	100	100	100	100	100	100
X''d Direct-axis subtransient reactance saturated	7.1	8.1	7.9	8.8	9.3	10	10.2	9.9	10.1	11.3
T''d Subtransient time constant	10	10	10	10	10	10	10	10	10	10
X''q Quadrature-axis subtransient reactance saturated	16.1	18.3	17	18.9	18.9	20.4	20.4	19.5	19.7	21.9
Xo Zero sequence reactance	0.49	0.56	0.55	0.61	0.64	0.69	0.7	0.68	0.7	0.78
X2 Negative sequence reactance saturated	11.62	13.28	12.53	13.92	14.12	15.25	15.31	14.74	14.96	16.62
Ta Armature time constant	15	15	15	15	15	15	15	15	15	15

Other class H / 400 V data

io (A) No-load excitation current SHUNT	0.84	0.84	0.8	0.8	0.67	0.67	0.66	0.68	0.64	0.64
io (A) No-load excitation current AREP	1.08	1.08	1.03	1.03	0.87	0.87	0.85	0.88	0.82	0.82
ic (A) On-load excitation current SHUNT	2.6	2.95	2.75	3.08	2.57	2.78	2.79	2.82	2.69	3.01
ic (A) On-load excitation current AREP	3.35	3.8	3.54	3.96	3.31	3.59	3.6	3.63	3.46	3.88
uc (V) On-load excitation voltage SHUNT	28.9	32.5	30.1	33.2	31.9	34.3	34.1	34.1	20.1	22.2
uc (V) On-load excitation voltage AREP	23.2	26.1	24.1	26.7	25.6	27.5	27.4	27.4	15.8	17.5
ms Response time ($\Delta U = 20\%$ transient)	500	500	500	500	500	500	500	500	500	500
kVA Start ($\Delta U = 20\%$ cont. or $\Delta U = 30\%$ trans.) SHUNT*	124	124	143	143	204	205	225	254	318	318
kVA Start ($\Delta U = 20\%$ cont. or $\Delta U = 30\%$ trans.) AREP*	149	149	171	171	246	245	269	306	402	402
% Transient ΔU (on-load 4/4) SHUNT - P.F.: 0.8 _{LAG}	17.2	18.8	18.5	19.9	18.2	19.1	19.3	18.9	17.3	18.6
% Transient ΔU (on-load 4/4) AREP - P.F.: 0.8 _{LAG}	15.2	16.6	16.4	17.6	16.1	16.9	17.1	16.7	13.2	14.2
W No-load losses	1980	1980	2175	2175	2322	2322	2478	2785	2665	2665
W Heat dissipation	5903	7091	6931	8053	8255	9254	9769	10184	10134	11898

* P.F. = 0.6

Reactances (%). Time constants (ms) - Class H / 480 V

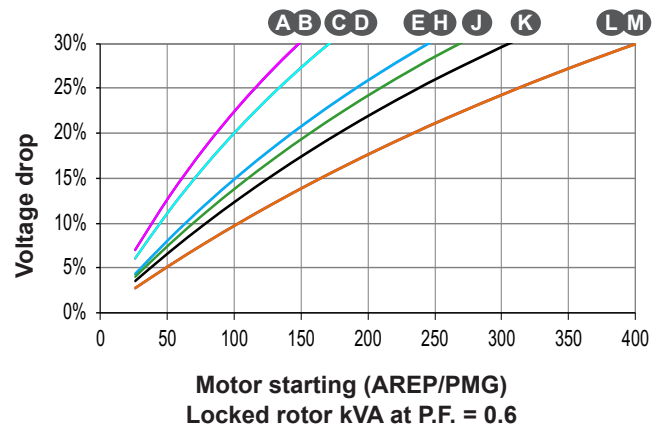
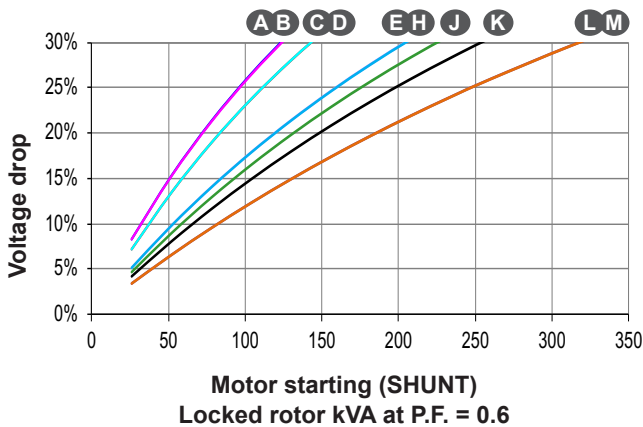
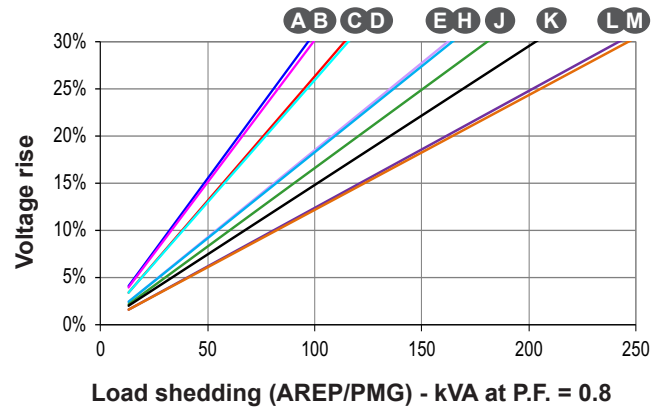
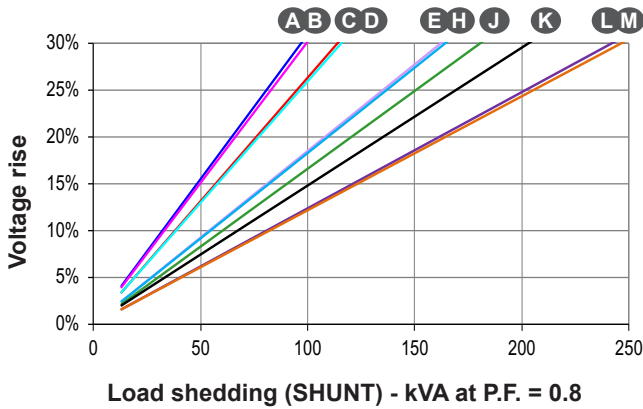
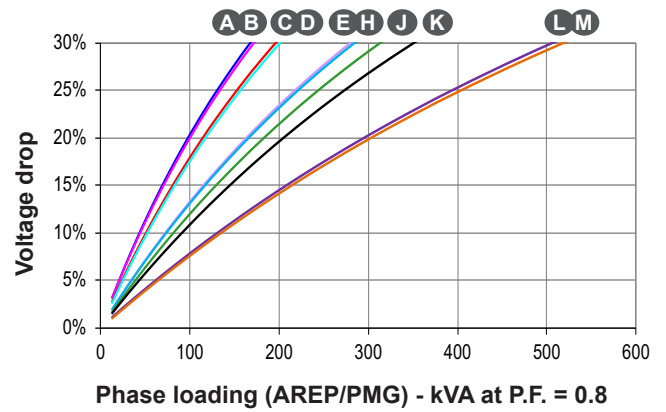
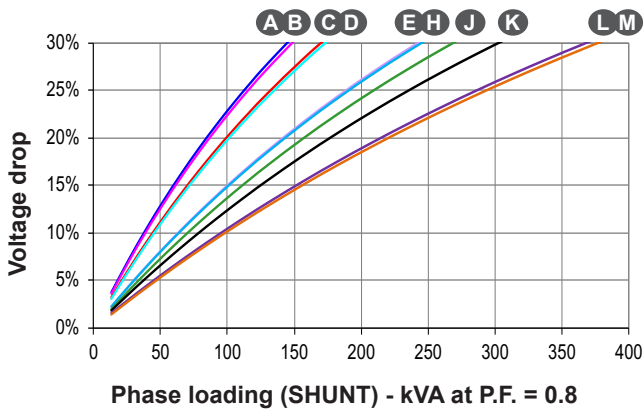
	A	B	C	D	E	H	J	K	L	M
Kcc Short-circuit ratio	0.55	0.48	0.5	0.46	0.41	0.38	0.38	0.41	0.36	0.32
Xd Direct-axis synchro. reactance unsaturated	308	350	321	355	348	377	375	356	358	397
Xq Quadrature-axis synchro. reactance unsaturated	157	178	164	181	177	192	191	182	182	202
T'do No-load transient time constant	2475	2475	2308	2308	2154	2154	2112	2077	2025	2025
X'd Direct-axis transient reactance saturated	12.4	14.1	13.9	15.4	16.1	17.5	17.7	17.1	17.6	19.6
T'd Short-circuit transient time constant	100	100	100	100	100	100	100	100	100	100
X''d Direct-axis subtransient reactance saturated	7.4	8.5	8.3	9.2	9.7	10.5	10.6	10.3	10.6	11.7
T''d Subtransient time constant	10	10	10	10	10	10	10	10	10	10
X''q Quadrature-axis subtransient reactance saturated	16.8	19.1	17.8	19.7	19.6	21.3	21.3	20.3	20.5	22.8
Xo Zero sequence reactance	0.51	0.59	0.58	0.64	0.67	0.72	0.74	0.71	0.73	0.81
X2 Negative sequence reactance saturated	12.17	13.83	13.1	14.49	14.69	15.91	15.99	15.34	15.59	17.32
Ta Armature time constant	15	15	15	15	15	15	15	15	15	15

Other class H / 480 V data

io (A) No-load excitation current SHUNT	0.84	0.84	0.79	0.79	0.67	0.67	0.66	0.68	0.63	0.63
io (A) No-load excitation current AREP	1.08	1.08	1.02	1.02	0.87	0.87	0.85	0.87	0.82	0.82
ic (A) On-load excitation current SHUNT	2.6	2.91	2.72	3.01	2.58	2.79	2.79	2.79	2.69	3
ic (A) On-load excitation current AREP	3.34	3.76	3.51	3.88	3.32	3.59	3.6	3.59	3.47	3.87
uc (V) On-load excitation voltage SHUNT	29.3	32.6	30.3	33.3	32.4	34.8	34.7	34.4	20.4	22.6
uc (V) On-load excitation voltage AREP	23.5	26.2	24.4	26.7	26	28	27.8	27.6	16.1	17.8
ms Response time ($\Delta U = 20\%$ transient)	500	500	500	500	500	500	500	500	500	500
kVA Start ($\Delta U = 20\%$ cont. or $\Delta U = 30\%$ trans.) SHUNT*	149	150	172	172	246	246	270	304	381	381
kVA Start ($\Delta U = 20\%$ cont. or $\Delta U = 30\%$ trans.) AREP*	179	179	205	207	295	296	322	366	521	521
% Transient ΔU (on-load 4/4) SHUNT - P.F.: 0.8 _{LAG}	17.7	19.3	19.1	20.4	18.6	19.7	19.9	19.4	17.8	19.1
% Transient ΔU (on-load 4/4) AREP - P.F.: 0.8 _{LAG}	15.7	17.1	16.9	18.1	16.5	17.4	17.6	17.2	13.6	14.6
W No-load losses	2905	2905	3189	3189	3417	3417	3639	4070	3923	3923
W Heat dissipation	7042	8265	8222	9378	9683	10805	11438	11913	12145	14130

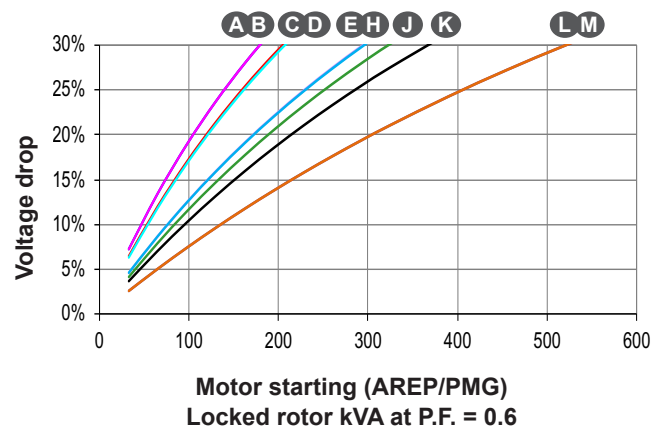
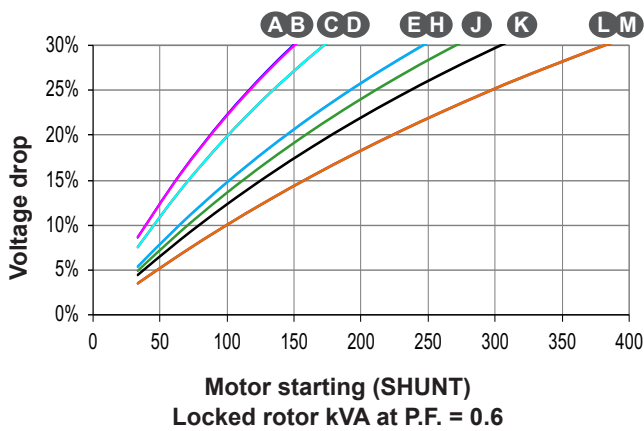
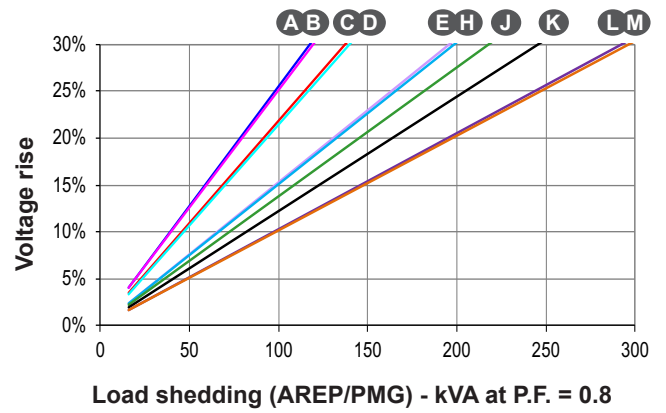
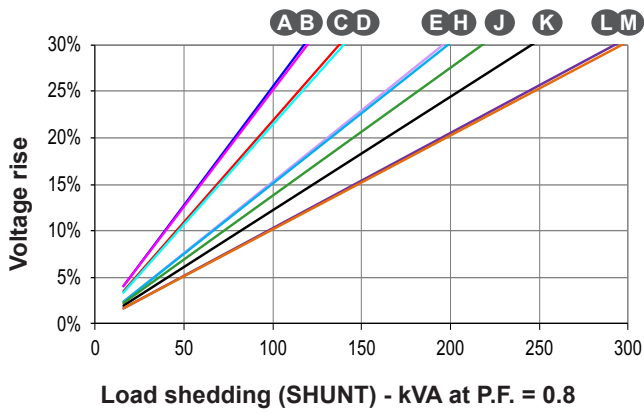
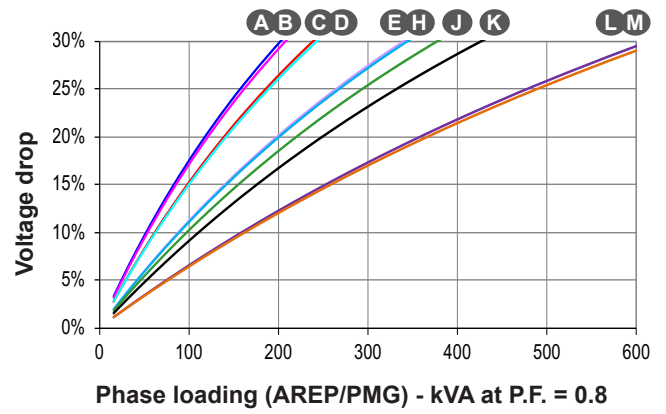
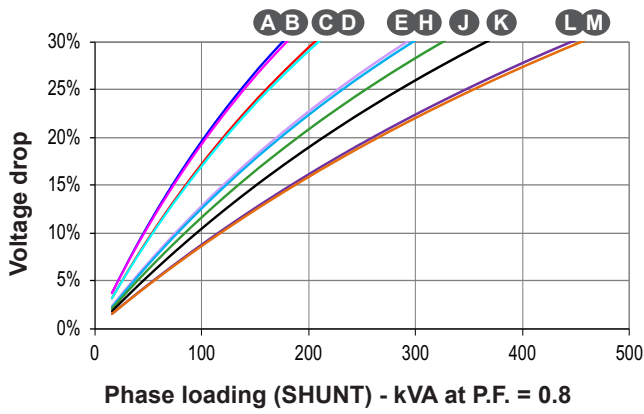
* P.F. = 0.6

Transient voltage variation 400V - 50 Hz



- 1) For a starting P.F. other than 0.6, the starting kVA must be multiplied by $K = \text{Sine P.F.} / 0.8$
- 2) For voltages other than 400V (Y), 230V (Δ) at 50 Hz, then kVA must be multiplied by $(400/U)^2$ or $(230/U)^2$.

Transient voltage variation 480V - 60 Hz

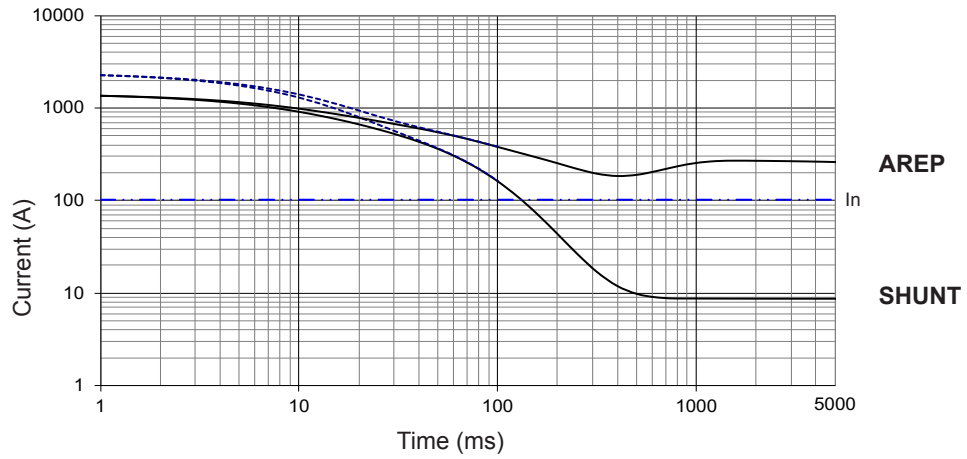


- 1) For a starting P.F. other than 0.6, the starting kVA must be multiplied by $K = \text{Sine P.F.} / 0.8$
- 2) For voltages other than 480V (Y), 277V (Δ), 240V (YY) at 60 Hz, then kVA must be multiplied by $(480/U)^2$ or $(277/U)^2$ or $(240/U)^2$.

3-phase short-circuit curves at no load and rated speed (star connection Y)

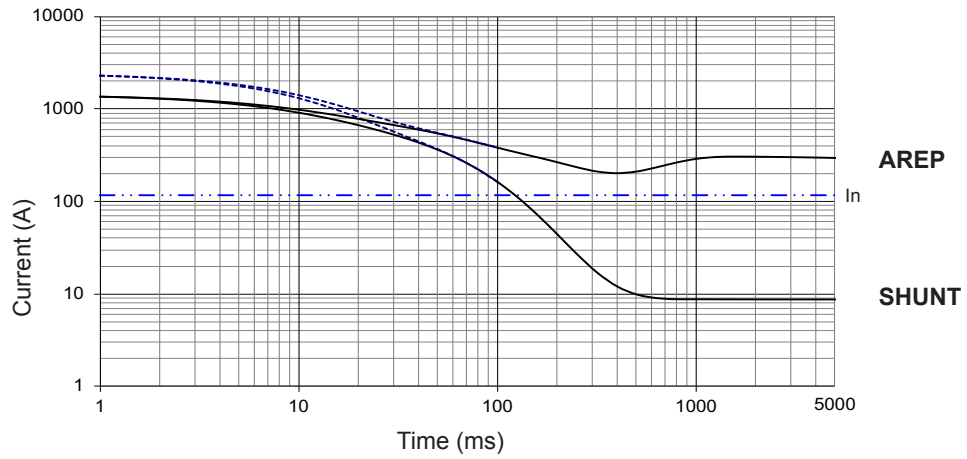
TAL 044 A

Symmetrical —
Asymmetrical - - -



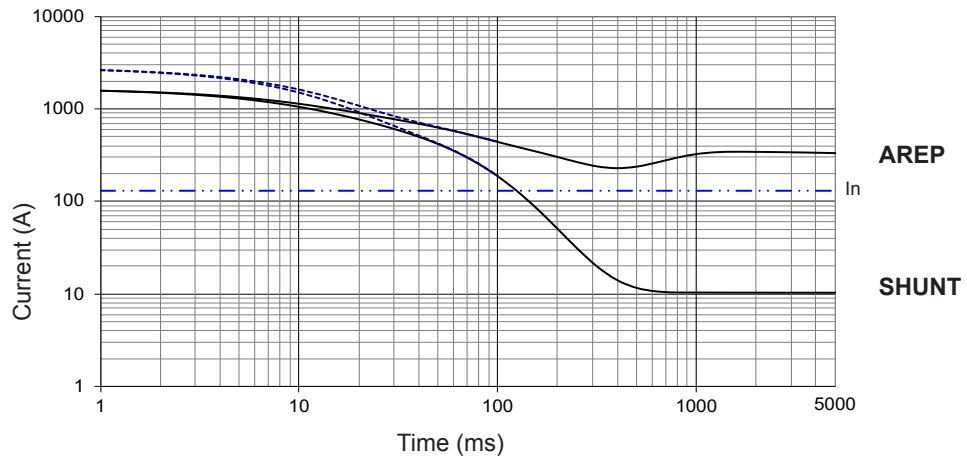
TAL 044 B

Symmetrical —
Asymmetrical - - -



TAL 044 C

Symmetrical —
Asymmetrical - - -



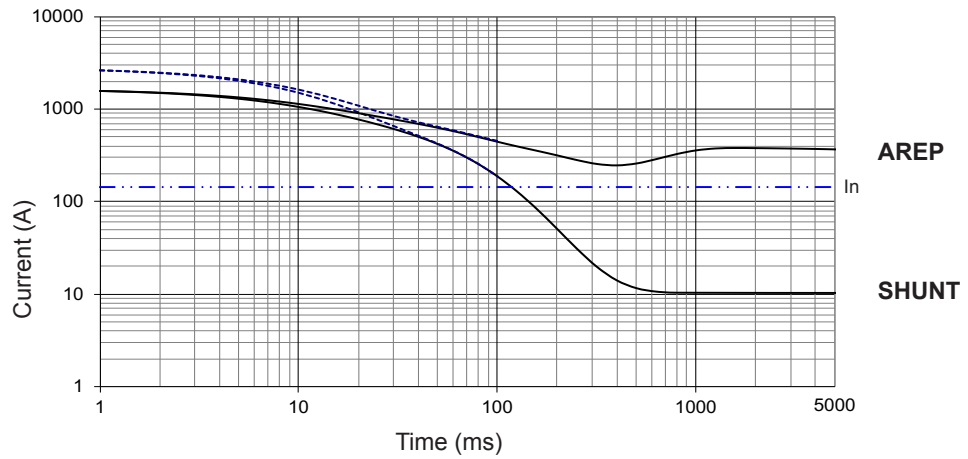
Influence due to connection

For (Δ) connection, use the following multiplication factor:
- Current value x 1.732.

3-phase short-circuit curves at no load and rated speed (star connection Y)

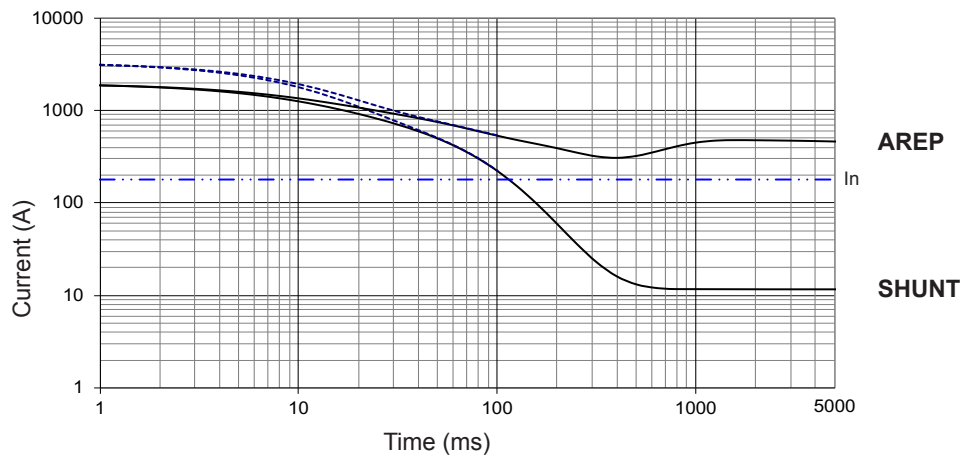
TAL 044 D

Symmetrical —
Asymmetrical - - -



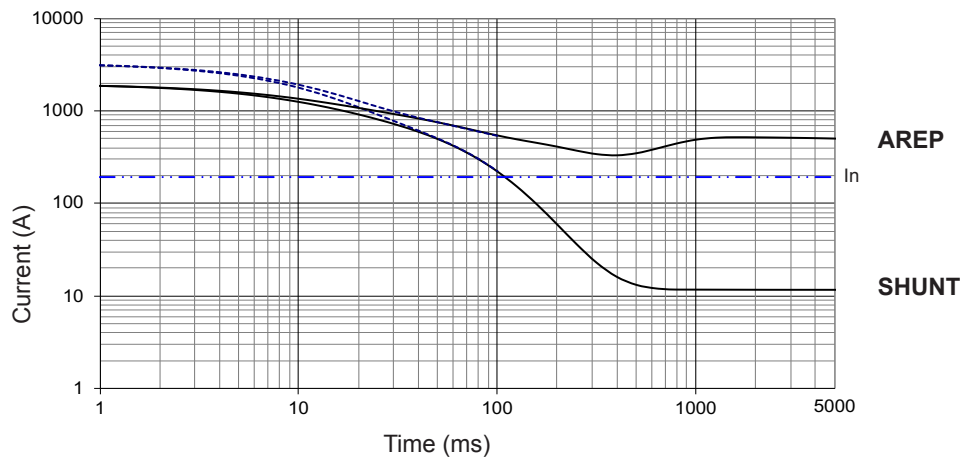
TAL 044 E

Symmetrical —
Asymmetrical - - -



TAL 044 H

Symmetrical —
Asymmetrical - - -



Influence due to short-circuit

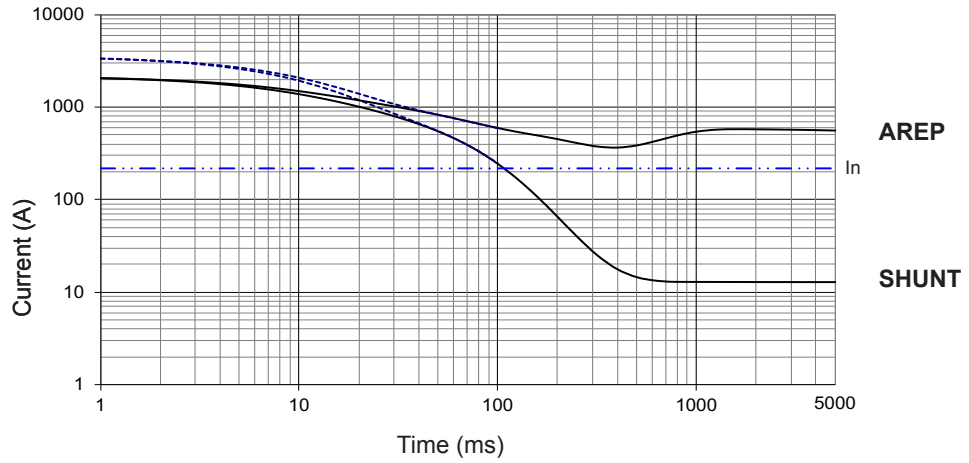
Curves are based on a three-phase short-circuit.
For other types of short-circuit,
use the following multiplication factors.

	3 - phase	2 - phase L / L	1 - phase L / N
Instantaneous (max.)	1	0.87	1.3
Continuous	1	1.5	2.2
Maximum duration		1.5	

3-phase short-circuit curves at no load and rated speed (star connection Y)

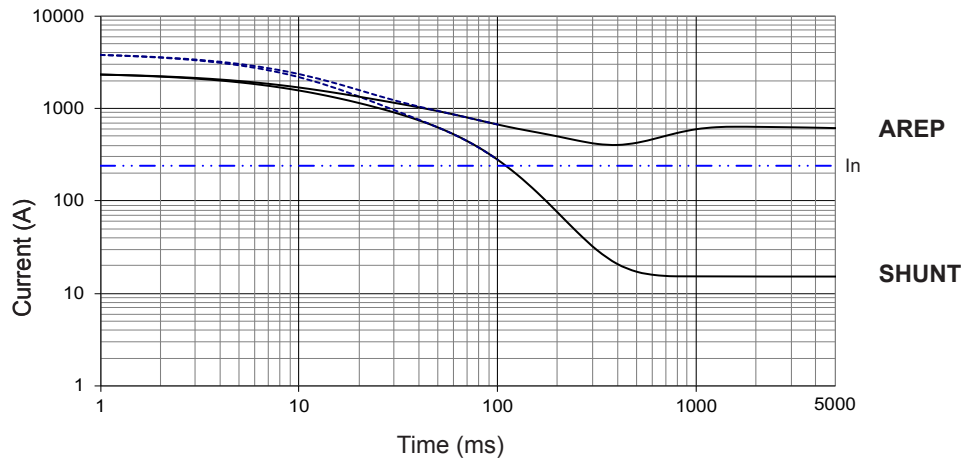
TAL 044 J

Symmetrical —
Asymmetrical - - -



TAL 044 K

Symmetrical —
Asymmetrical - - -



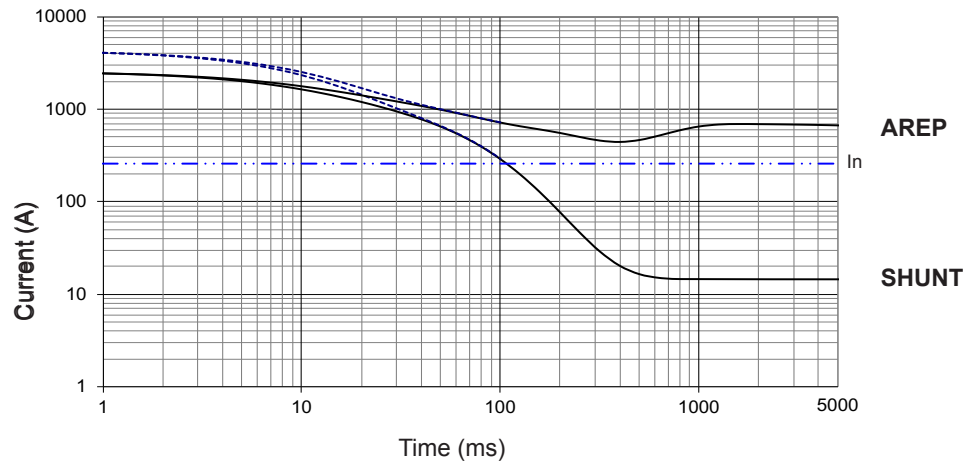
Influence due to connection

For (Δ) connection, use the following multiplication factor:
- Current value x 1.732.

3-phase short-circuit curves at no load and rated speed (star connection Y)

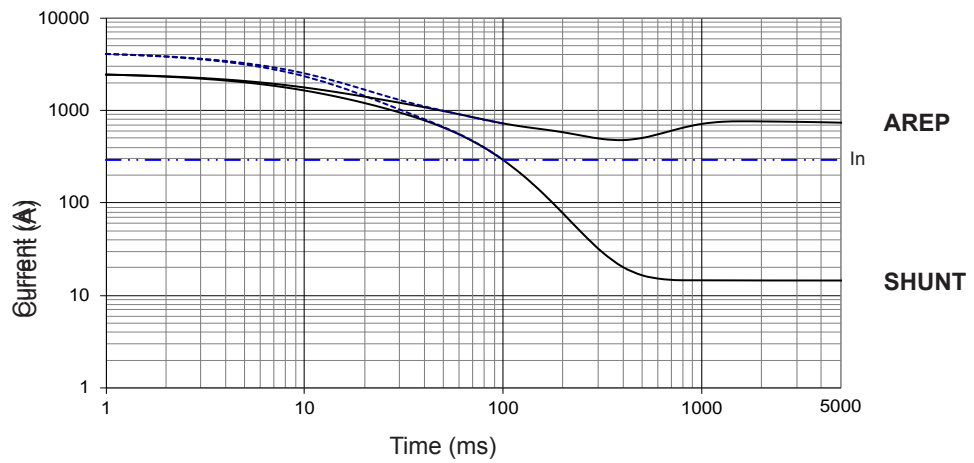
TAL 044 L

Symmetrical —
Asymmetrical - - -



TAL 044 M

Symmetrical —
Asymmetrical - - -



Influence due to short-circuit

Curves are based on a three-phase short-circuit. For other types of short-circuit, use the following multiplication factors.

	3 - phase	2 - phase L / L	1 - phase L / N
Instantaneous (max.)	1	0.87	1.3
Continuous	1	1.5	2.2
Maximum duration		1.5	

TAL 044 - Dedicated single-phase 57 to 82 kVA - 50 Hz / 80 to 125 kVA - 60 Hz

General characteristics

Insulation class	H	Excitation system	SHUNT
Winding pitch	2/3 (wind. M 50Hz, M1 60Hz)	AVR type	R121
Number of wires	4	Voltage regulation (*)	± 1 %
Protection	IP 23	Total Harmonic Distortion THD (**) in no-load	< 3.5 %
Altitude	≤ 1000 m	Total Harmonic Distortion THD (**) in linear load	< 5 %
Overspeed	2250 R.P.M.	Waveform: NEMA = TIF (**)	< 100
Air flow (m³/s)	50 Hz: 0.25 - 60 Hz: 0.30	Waveform: I.E.C. = FHT (**)	< 2 %

(*) Steady state (**) Total harmonic distortion between phases, no-load or on-load (non-distorting)

Ratings / Efficiencies 50 Hz - 1500 R.P.M. - Winding M

kVA / kW - P.F. = 1(*)							
Duty / T° C	Continuous / 40 °C		Continuous / 40 °C	Stand-by / 40 °C	Stand-by / 27 °C		
Class / T° K	H / 125° K		F / 105° K	H / 150° K	H / 163° K		
Serie (SE)	230 V		η %	230 V	230 V	230V	η %
TAL 044 C	57	91	52	60	63	90.7	
TAL 044 D1	69	91.5	63	73	76	91.1	
TAL 044 E	-	-	-	-	-	-	
TAL 044 J	82	92.3	75	87	90	92	
TAL 044 K	-	-	-	-	-	-	

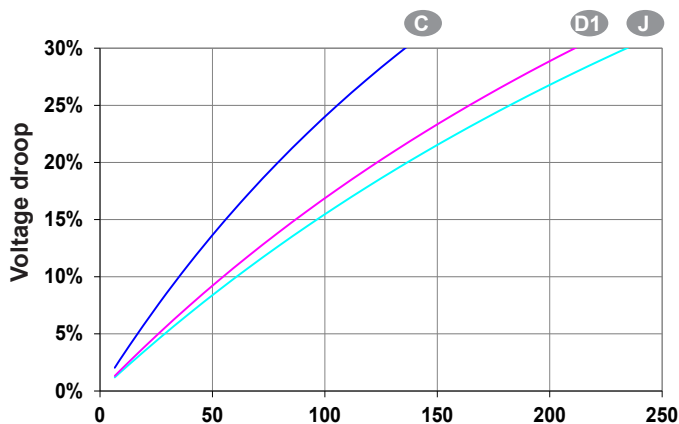
(*) For P.F. 0.8: derating 15%

Ratings / Efficiencies 60 Hz - 1800 R.P.M. - Winding M1

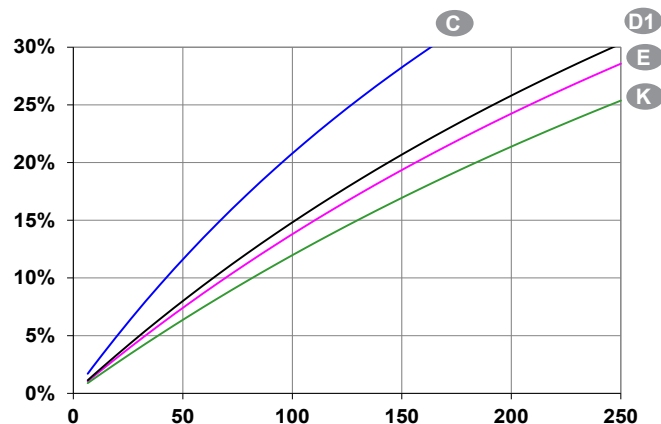
kVA / kW - P.F. = 1(*)							
Duty / T° C	Continuous / 40 °C		Continuous / 40 °C	Stand-by / 40 °C	Stand-by / 27 °C		
Class / T° K	H / 125° K		F / 105° K	H / 150° K	H / 163° K		
Serie (SE)	240 V		η %	240 V	240 V	240V	η %
TAL 044 C	80	90	73	85	88	89.7	
TAL 044 D1	100	90	91	106	110	89.7	
TAL 044 E	115	90.7	105	122	127	90.2	
TAL 044 J	-	-	-	-	-	-	
TAL 044 K	125	91.7	114	133	138	91.4	

(*) For P.F. 0.8: derating 15%

Starting motor 230V - 50Hz



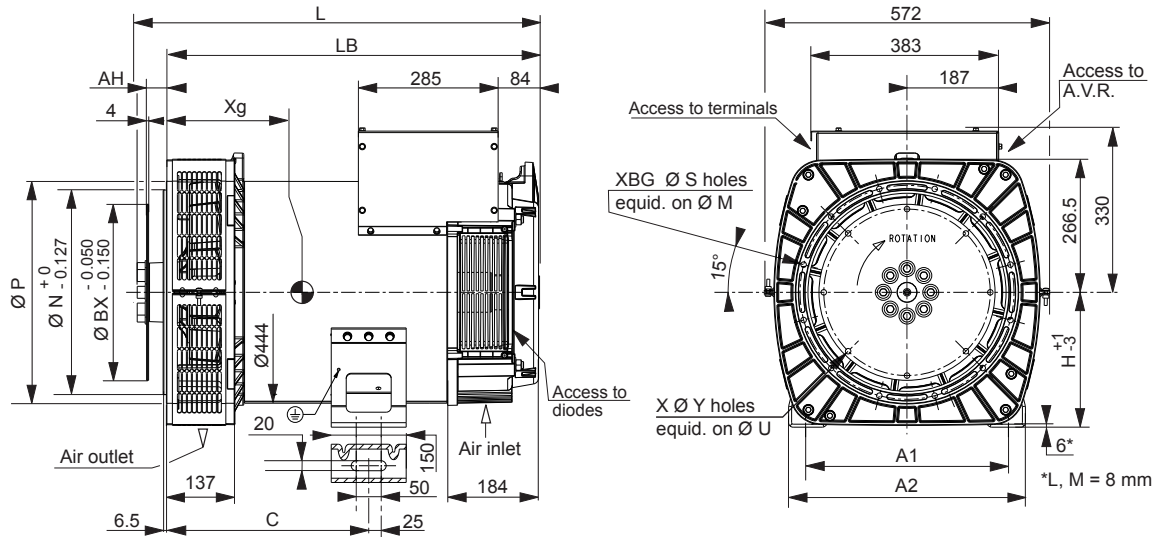
Starting motor 240V - 60Hz



Locked rotor kVA at PF : 0.9

TAL 044 - Three-phase & Single-phase

Single bearing general arrangement



Dimensions (mm) and weight				
Type	L maxi	LB	Xg	Weight (kg)
TAL 044 A	750	677	293	262
TAL 044 B	750	677	293	262
TAL 044 C	750	677	313	295
TAL 044 D	750	677	313	295
TAL 044 D1	750	677	313	295
TAL 044 E	820	747	353	368
TAL 044 H	820	747	353	368
TAL 044 J	820	747	365	398
TAL 044 K	860	787	383	433
TAL 044 L	930	872	416	554
TAL 044 M	930	872	416	554

Shaft height (mm)			
	Standard	Option	
H	270	225(*)	280(**)
Feet length			
C	405	332.5	429
A1	406	356	457
A2	474	474	541

Coupling			
Flange	1	2	3
11 1/2	x	x	x
10	x	x	x

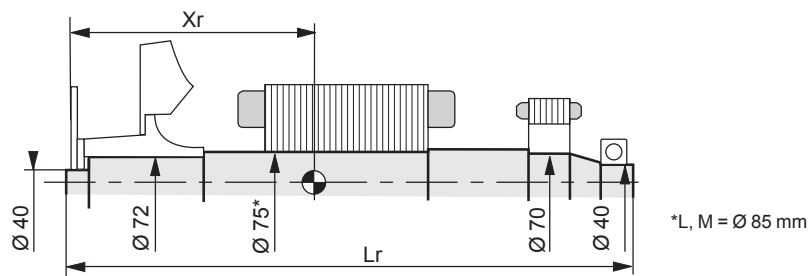
(*) not available for L and M
 (**) only for L and M

Flange (mm)					
S.A.E.	P	N	M	S	XBG
3	445	409.58	428.62	11	12
2	485	447.68	466.72	11	12
1	560.5(*)	511.18	530.23	12	10

Flex plate (mm)					
S.A.E.	BX	U	X	Y	AH
11 1/2	352.42	333.38	8	11	39.6
10	314.32	295.28	8	11	53.8

(*) L and M = 550 mm

Torsional data



Centre of gravity: Xr (mm), Rotor length: Lr (mm), Weight: M (kg), Moment of inertia: J (kgm²): (4J = MD²)									
Flex plate	S.A.E. 10				S.A.E. 11 1/2				
	Type	Xr	Lr	M	J	Xr	Lr	M	J
TAL 044 A		344.7	704	107.2	0.770	332.1	704	106.8	0.769
TAL 044 B		344.7	704	107.2	0.770	332.1	704	106.8	0.769
TAL 044 C		355.2	704	121	0.894	342.4	704	120.6	0.893
TAL 044 D		355.2	704	121	0.894	342.4	704	120.6	0.893
TAL 044 D1		376.1	704	139.1	1.051	363.2	704	138.7	1.050
TAL 044 E		400.2	774	153.7	1.167	387.2	774	153.3	1.166
TAL 044 H		400.2	774	153.7	1.167	387.2	774	153.3	1.166
TAL 044 J		411	774	165.5	1.274	398	774	165.1	1.273
TAL 044 K		431	814	180.6	1.409	417.9	814	180.2	1.408
TAL 044 L		465	914	224.1	1.753	450.7	899	223.7	1.769
TAL 044 M		465	914	224.1	1.753	450.7	899	223.7	1.769

Consult us for S.A.E. 14, 8,...

NOTE : Dimensions are for information only and may be subject to modifications. The torsional analysis of the transmission is imperative. All values are available upon request.

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